## Debugging CUDA

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GECCO 2011 Companion, pages 415-422



#### Introduction

- Some ideas on debugging GPGPU code
- 1<sup>st</sup> of two parts. 2<sup>nd</sup> part on performance
- Code level debug aids, rather than tools
- Testing
- Example errors
- Lessons



## Defensive Programming

- Hard to debug kernel which fails because get no feed back.
- Write description of all kernel parameters before each is started to a log file.

kernel<<<grid\_size, block\_size, shared\_size>>>
(height,width,len,d\_in,d\_a,d\_y,d\_out1,d\_out2,d\_status);
cutilCheckMsg("kernel() execution failed.\n");



# Defensive Programming - Loops

- In most kernels there are no loops or only one
- Trap all potential infinite loops inside kernel

```
int loop = 0; //prevent looping forever
do {
   if(found) break;
   if(empty) break;
   //next
} while(loop++ < Nvalue);</pre>
```



### Kernel Launch Failure

- Always check kernel status immediately with cutilCheckMsg("kernel\_name execution failed.\n");
  - This (and your log) will help you pinpoint which kernel failed.
  - Sometimes the cutil error message can help
- cuda-memcheck --continue can sometimes locate array bound errors inside your kernel. Too slow for normal use.



#### First Kernel

- Write a kernel which does nothing except check:
  - Does input reach the kernel?
  - Does output leave the kernel?
  - Do threads put data in correct place?
  - Is output correct?

```
static __global__ void kernel(
    const int LEN,
    int d_1D_out[1000] //check kernel creates correct output
) {
    const int tid = blockDim.x * blockIdx.x + threadIdx.x;
    const int threadN = blockDim.x * gridDim.x;
    for(unsigned int t = tid; t < LEN; t += threadN){
        d_1D_out[t] = threadIdx.x;
    }
}</pre>
```



# Debugging your First Kernel

- Did your first kernel work?
- Test your debugging system by adding an error.
- Did the kernel fail in the way you expected?
- Did your error trapping code catch the error and report it?
- Did your revision control system allow you to recover your working version reliably, correctly, with a minimum of manual input?



#### Debug

- More examples of debug code in paper.
- Saving GPU buffers
- Testing...



# Testing

- New code is wrong
- Modified code is wrong
- Testing is second best way of finding errors
- Testing Evolutionary Algorithms
- Comparison with known answers
- Regression Testing
- Source code version management



# Testing GAs

- Evolutionary Algorithms can evolve high scoring "solutions".
- "Solution" can be a bug in fitness function.
   Eg robotics simulations.
- EA can work around bug in itself
- Do not assume your system is working because it evolves good looking answers



#### Comparison with Known Answers

- Are there benchmarks with correct answers?
- Is there a serial version (is it bug free)?
- Can you easily create a serial version?
  - Need not be efficient, just correct



#### Comparison with Known Answers

- Easy to overlook differences and assume they are small and unimportant.
- Insist your GPU produces identical answers.
- Carefully control use of random seeds
- With floating point GPU will produce different answers.
  - Decide in advance size of acceptable difference
  - Do you want -0, NaN etc to be "different"?



## **Regression Testing**

- Modified code is wrong
- Comparing your "improved" code's output with previous outputs can help locate errors.



### **Revision Control**

- Modified code is wrong
- The best way of locating faults is comparing your "improved" code with the previous version.
- Your revision control system should make it easy to compare versions of your code.
- Ensure you have an automated way of recording which version of your code produced which outputs. This can help greatly in regression testing.



## **GPU Bugs**

- Too many examples!!!
  - For example, see proceedings (pages 415-423)
- I have chosen three related to GPU

# GPU Bugs – Missing threads

```
__device__ void save_data(const unsigned int mask,...) {
    ...
}
...
if(data) {
    ... lookup data ...
    if(missing) save_data(data,...);
}
```

- From the calling code, we can see save\_data() is only called by threads for which data is both non-zero and missing.
- This is not obvious when looking at save\_data()'s code. Where I assumed all threads in a warp were calling it.



#### volitile

- volatile turns off nvcc optimisation whereby it uses per thread registers.
- Using shared memory to communicate between threads
- Make every pointer to shared memory volatile



# C not fully defined, int >>24

- C right shift operation can either perform an arithmetic or a logical shift.
- To fix this I declared the variable unsigned int rather than int



### Discussion

- Debug driven from host
  - printf, GPU debug direct to monitor, GPU emulator gone
- CUDA
  - CUDA works
    - Mostly (nvcc etc pretty stable) visual profiler poor
  - C, I guess you can have bugs in other languages
     openCL
- Linux
  - Eclipse?
  - Microsoft visual studio?
- Commercial Tools?



#### Conclusions

- YOU ARE THE BOOTLE NECK
- Writing working high performance GPGPU code is hard.
- Four CIGPU events BUT creating evolutionary algorithms to effectively use GPU is still hard
- Establish libraries of debugged code?
- Can problem be expressed as matrix manipulation? Use cublas library?

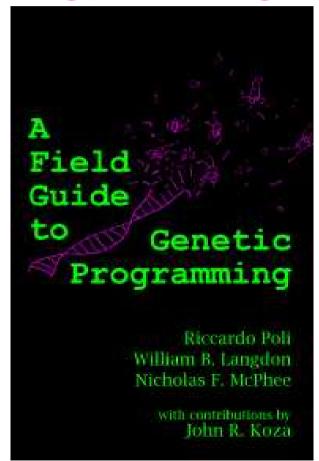


## END

http://www.epsrc.ac.uk/ EPSRC

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#### A Field Guide To Genetic Programming http://www.gp-field-guide.org.uk/



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#### The Genetic Programming Bibliography

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