

Visibility Determination

©Anthony Steed, Yiorgos Chrysanthou 1999-2003,
Celine Loscos 2005, Jan Kautz 2007-2009

Overview

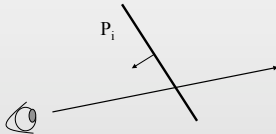
- Why visibility culling?
 - Avoid *incorrect* image being displayed
 - Enables speed-up
- With ray casting, visibility was solved implicitly in image space
 - Now we are projecting polygons, we need to address this directly
 - Z-Buffering is one solution to it
 - We want to look at other solutions

Types of Visibility Methods

- Back-face elimination
 - List priority
 - Ordering in Projection Space
 - Depth-sort
 - Ordering in Object Space
 - Binary Space Partition Trees
 - Image precision, e.g.
 - Z-buffer
 - Ray Casting
- } Already seen these methods

Back Face Culling

- We were specifying the order (clockwise or counter clockwise) for a reason
- Polygons whose normal does not face the viewpoint, are not rendered



Back Face Culling

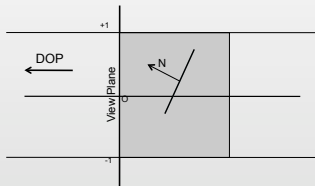
- Thus if we have the plane equation

$$l(x, y, z) = ax + by + cz - d = 0$$
- and the COP (c_x, c_y, c_z) , then

$$l(c_x, c_y, c_z) > 0$$
- if the COP is in *front* of the polygon
- Otherwise: cull

Back Facing Culling

- Alternatively, think about projection space
 - The transformed polygon must have a normal N with a negative z component to be visible



Calculating the Normal (of transformed poly)

- If the plane equation is expressed so:

$$p \cdot l = 0$$

$$(x, y, z, 1) \cdot \begin{bmatrix} a \\ b \\ c \\ -d \end{bmatrix} = 0$$

Reminder: (a, b, c) is the normal of the plane

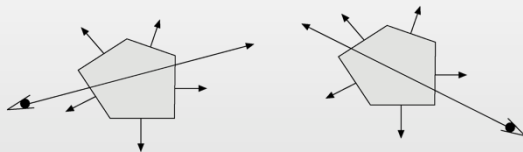
- Suppose T is the modelview matrix and thus transformed point q is $q = pT$

Calculating the Normal (of transformed poly)

- If $q = pT$
- Then $qT^{-1} = p$
- So $qT^{-1} \cdot l = p \cdot l$
- Let $m = T^{-1} \cdot l = l \cdot (T^{-1})^T$
- Then $q \cdot m = 0$ ($= p \cdot l$)
- Therefore transform plane equation by inverse transpose of modelview transform
- Note, that x-formed normal might need rescaling

Back Face Culling

- Final words – for a *single convex* object, ANY order of polygons is correct (assuming backface culling)



Back Face Culling Summary

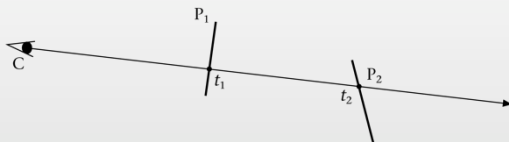
- Enables **speedup** by not drawing unnecessary polygons
- Does not ensure correct drawing order for visible surfaces, unless there is only a single convex object

Visibility Methods

- Back-face elimination
 - List priority
 - Ordering in Projection Space
 - Depth-sort
 - Ordering in Object Space
 - Binary Space Partition Trees
 - Image precision, e.g.
 - Z-buffer
 - Ray Casting
- } Already seen these methods

Visibility (Priority) Ordering – Painters Algorithm

- Given a set of polygons S and a viewpoint C :
Find an ordering on S
 - such that for any 2 polygons intersected by a ray through C , P_i has higher priority than P_j

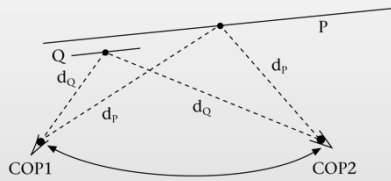


- You would render P_2 THEN P_1 to see correct result

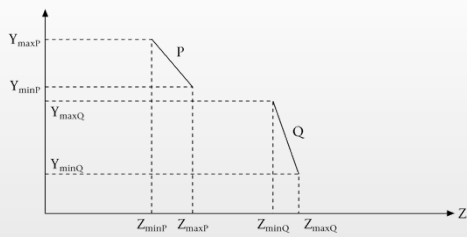
Painters Algorithm

Z-Sort in Projection Space

- Simply sort back to front all polygons based on their mid-point
- Doesn't always work, e.g.



Depth-Sort (Newell et al. 72)



- Note that two polygons P&Q can be rendered in any order, if they do not overlap in X-Y
- P can be rendered before Q if P's z range is completely behind Q's

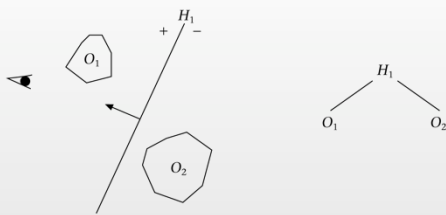
Depth-Sort

- P can be rendered before Q if
 - Z-extent of Q is wholly in front of P **or**
 - Y-extent of Q does not overlap P **or**
 - X-extent of Q does not overlap P **or**
 - All points on P lie on the opposite side of Q than the COP **or**
 - All points on Q lie on the same side of P as the COP **or**
 - The projections of P and Q on the XY plane do not overlap (full 2D polygon overlap test)
- Conclusions: expensive

Object Space Methods

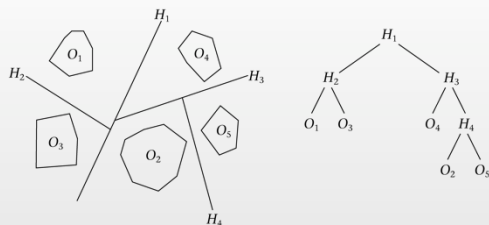
- Depth-sort tells us the relationship between a set of polygons, but must be computed every time
- However we know that most of the time objects do not intersect
- Can we work in object space to find gross relationship between the objects O1 and O2 so that we know all polygons in O1 can be rendered before O2 ?

Schumacker 69



- You can define a plane such that: a polygon/object on the same side as the viewpoint has higher priority than one on the opposite side

Schumacker 69



- If we have more than one object on one side then repeat the same reasoning and add more partitioning planes between these objects

Other Uses of Culling

- Done enough to ensure **correct** view, but we can do more to ensure **speed** (in the advanced course, next semester)
- View Volume Culling
- Visibility Culling
- Occlusion Culling

Summary

- Distinction between types of visibility algorithm
 - Projection space
 - Object space
 - Image space
- Back face culling as a *preliminary* step
- How priority ordering can be achieved through depth-sort and object-space methods
