

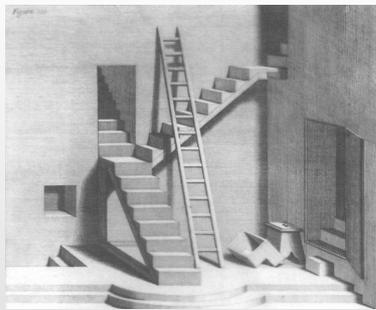
Shadow Algorithms

Outline

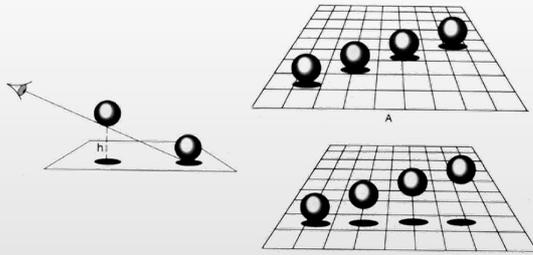
- Introduction
- Sharp shadows
- Soft shadows
- Conclusion

Why are Shadows Important?

- Depth cue
- Scene Lighting
- Realism
- Contact points



Shadows as a Depth Cue / Spatial Relation



For Intuition about Scene Lighting

- Position of the light (e.g. sundial)
- Hard shadows vs. soft shadows
- Colored lights
- Directional light vs. point light



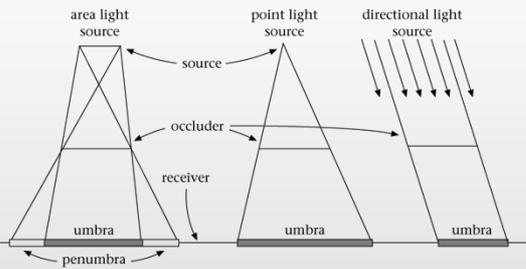
Shadows are Complex

- In the real world sources of light are not points
- The intensity within a shadow is not constant
 - umbra, the part that sees nothing of the source
 - penumbra, part that receives some light
- In computer graphics we simplify and cheat

Definition

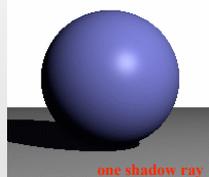
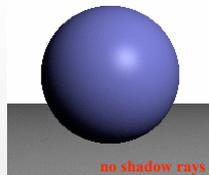
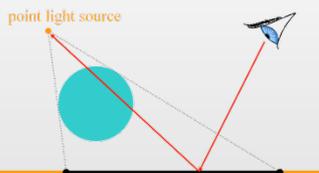


Definition



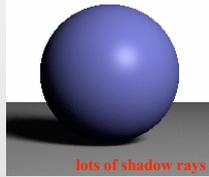
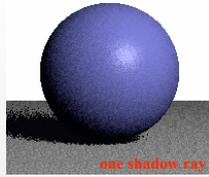
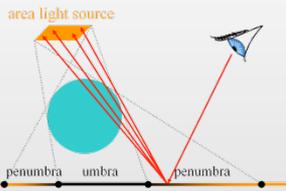
Shadows

- One shadow ray per intersection per point light source



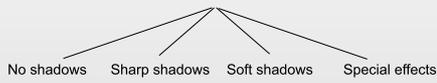
Soft Shadows

- Multiple shadow rays to sample area light source



Current Shadowing Methods

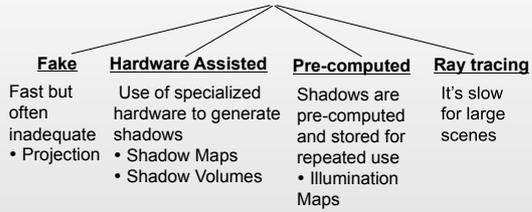
- There exist a very large number of methods
- We are interested in methods suitable for interactive walkthroughs, speed is crucial
- We will classify them by complexity:



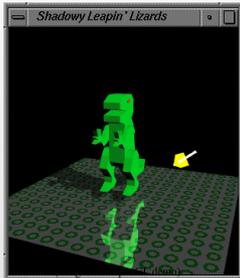
Sharp Shadows

Sharp Shadows

Source is assumed to be a point or direction



Fake Shadows: Projection on Ground



- Objects are compressed using a matrix transformation and pasted to the ground
- No inter-object shadows
- Very fast

Shadow Maps

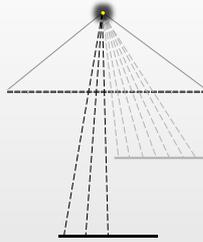
- Compute a Z-buffer from the source
 - use the light source as a view point and render the objects to get the depth information (shadow Z-buffer)
- Run a normal Z-buffer with shadow calculation
 - from the view point,
 - each pixel $P(x_v, y_v, z_v)$ in this buffer is mapped to the shadow buffer (x_s, y_s, z_s) ,
 - if the z_s value is less or equal to that stored there then the point is lit,
 - otherwise is in shadow

Shadow Maps

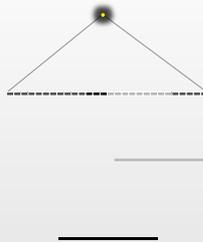


[Williams '78]

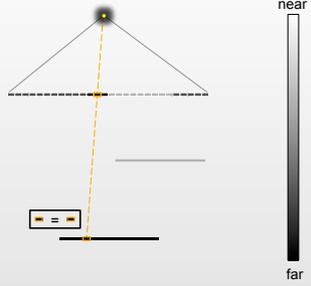
Shadow Maps



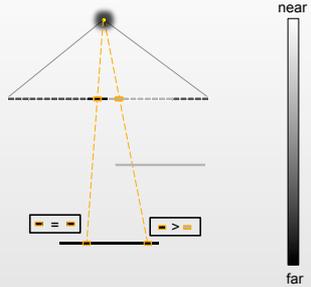
Shadow Maps



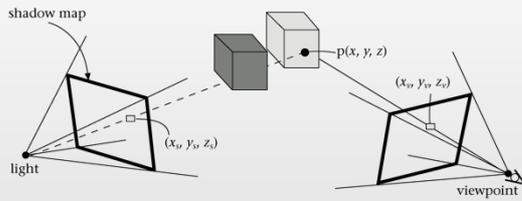
Shadow Maps



Shadow Maps



Shadow Maps



Shadow Maps with OpenGL

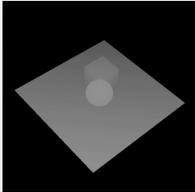
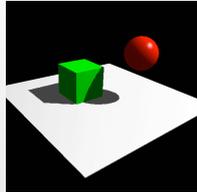


Image from source



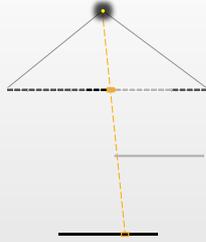
Resulting shadows

- This technique can be accelerated by using texture mapping hardware

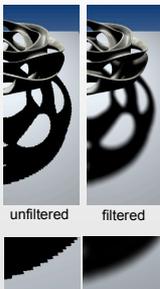
Shadow Map Filtering



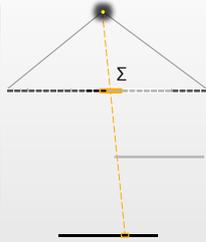
unfiltered



Shadow Map Filtering



unfiltered filtered

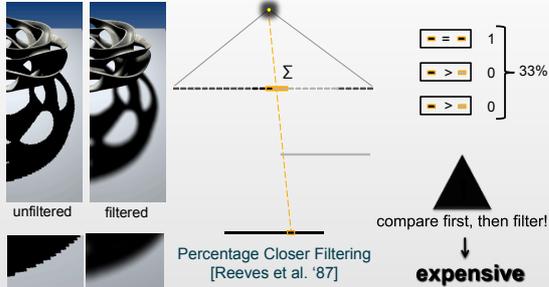


	1
	0
	0

33%

Percentage Closer Filtering
[Reeves et al. '87]

Shadow Map Filtering



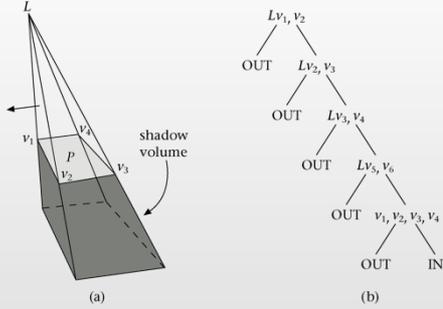
Shadow Maps

- "Less than or equal" test is imprecise
 - Gives rise to "shadow acne"
- Often found in hardware now
 - Otherwise high cost operation
- Imprecise since it is only accurate in the image space of the light
 - Imagine a shadow throw over complex objects or long distances
- Quality depends on resolution (jagged edges)
 - Percentage-closer filtering helps
- FOV of shadow map?

Shadow Volume Method

- Shadow volume (SV) is the volume of space below a polygon that cannot see the source (a culled pyramid)
- During rendering of image, the line from a point visible through a pixel to the eye is intersected with all object SVs
- The number of intersections indicates if the point is in shadow or not

Shadow Volumes



Shadow Volumes

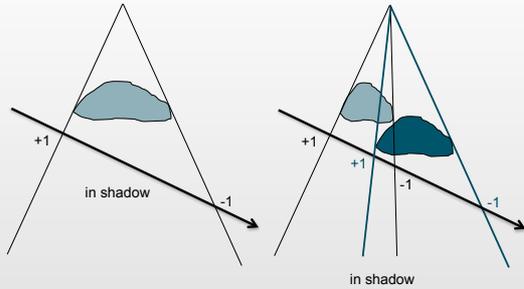
- Just like a polygon - you are inside a volume if you need to cross a surface to exit it
- General idea of shadow volumes is count the number of shadow planes you cross
 - +1 for front facing
 - -1 for back facing
- If total is >0 you are in shadow
- Special case if the eye itself is in shadow

Shadow Volumes

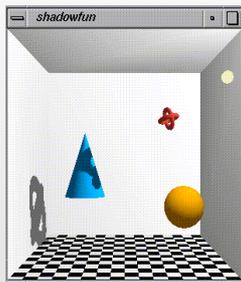
Two stages:

- 1) Preprocessing
 - Find all planes of the shadow volume and their plane equations
- 2) At run-time
 - Determine shadow plane count per pixel
 - Use a scan-line method OR stencil test

Shadow Volume Example



Shadow Volumes with OpenGL



(image from an SGI demo)

- Shadow volumes are rendered at each frame
- The stencil buffer is used for counting how many SV are crossed
- Sometimes not all objects are used for casting shadows

Shadow Volumes with Stencil Test

- A stencil buffer is screen sized buffer (1-8bit) that stores a flag about a rendering operation
 - E.G. $stencil[x,y]$ is negated if $zbuffer[x,y]$ is less than current z value (i.e. stencil is set if and only if z buffer test passes)
- Many uses in graphics

Shadow Volumes with Stencil Test

- Render the scene into the RGB and z-buffer
- Turn z-buffer *writing* off, then render all shadow polygons with the stencil buffer
 - Increment stencil count for front-facing
 - Decrement for back facing
- Re-render scene with lighting OFF and only render pixels where stencil is non-zero

Summary for sharp shadows

- Four shadow umbra techniques
- Image space
 - Shadow maps
 - Shadow volumes
- Object space
 - Fake shadows

Soft Shadows

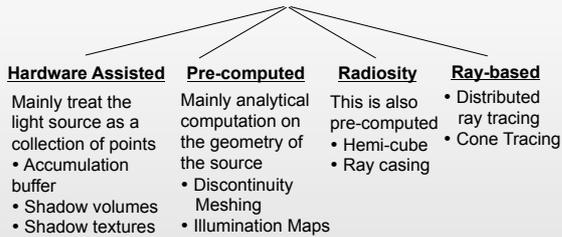
Soft Shadows

- Source has a finite extend
- Images look a lot more realistic



(Image taken from Nishita and Nakamae)

Soft Shadows



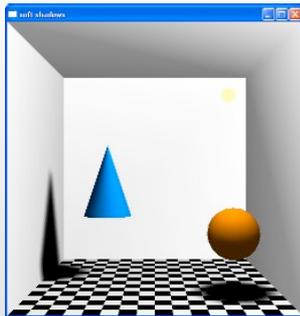
Analytical v. Sampling

- Analytical
 - Find all boundaries within the penumbra. Done almost exclusively for polygonal light sources
- Sampling
 - Approximate solution that treat the light source as a set of points. Any shape source is possible.

Soft Shadows using Point Light Source

- Place many point lights on an area light 
 - Random positions work just fine
- Render hard shadows from each point light
 - E.g., using shadow volumes or shadow maps
- Sum up all contributions
 - Can be done on the GPU (in the frame-buffer)
- Similar to what ray-tracing does to get soft shadows

Example



Illumination Maps (Shadow Textures)

- Shadows are pre-computed and stored as textures on the receiving polygons
- Displayed using graphics hardware in real-time
- Disadvantage: lighting cannot change

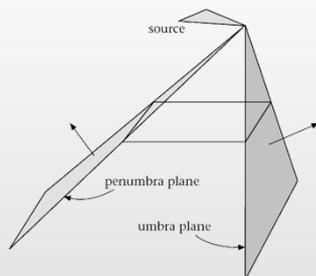
Analytical methods

- Find all boundaries within the penumbra. Done almost exclusively for polygonal light sources.

Extremal Shadow Boundaries

- What is the potential area of the penumbra and umbra?
- For penumbra:
 - Bounded by planes define by a pair of source vertex and occluder edge where the source is in the front space and the occluder on the back
- For umbra:
 - Similarly defined planes, but where source and occluder are in the back space

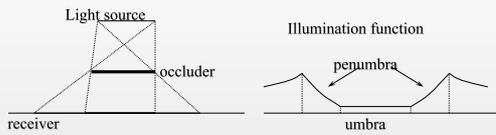
Extremal Shadow Boundaries



Shading Using Extremal Planes

- If you write these planes into object space
- We can use a scan-conversion as we have before
 - At each pixel we must estimate the proportion of the light source that can be seen
 - [Usually done with SVBSP tree(s)]

Discontinuity Meshing

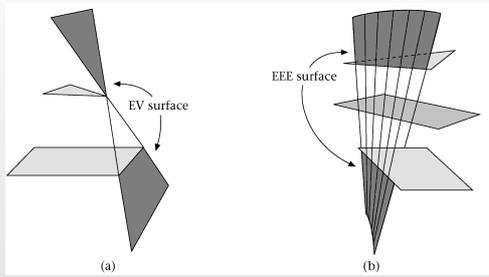


- Subdivide at discontinuity points
- Compute illumination intensity at discontinuity points
- Quadratic approximation on segments between discontinuity points

Discontinuity Meshing

- Borrowing aspect graphs from computer vision
- Define critical surfaces where visual events occur
 - EV surfaces: planes defined by edge and vertex
 - EEE surfaces: quadratic surfaces defined by three non-adjacent edges.
- Penumbra volumes so far have used EV only

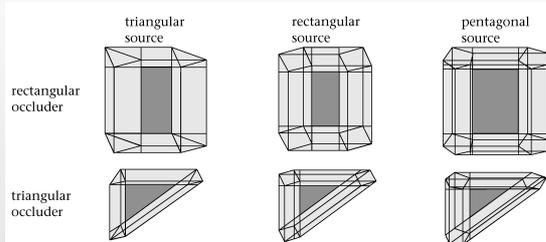
EV and EEE Surfaces



Discontinuity Meshing

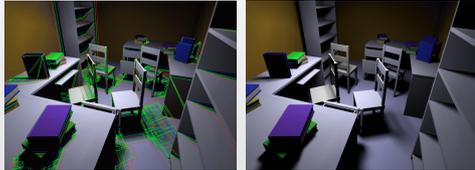
- Discontinuities of the illumination of a polygon occur at the places where EV and EEE surfaces intersect the polygon
- Discontinuities occur at different degrees
- Discontinuities are written into the geometry of the scene as before

Examples of meshes



Discontinuity Meshing

- Very high quality shadows
- Slow and prone to floating point errors



Radiosity

- Scene polygons are subdivided into a mesh, or the illumination is stored as a texture
- Very realistic results
- Good for static scenes but not for moving objects

Conclusion

- A very large number of shadow algorithms exist
- Many of them are unsuitable for walkthroughs of very complex scenes:
 - with pre-computation methods scene cannot be modified
 - or are too slow (ray-tracing, soft shadows)
- Hard shadows
 - on-the-fly methods (SM and SV) are fast enough
