

# Traceability in Viewpoint Merging: A Model Management Perspective

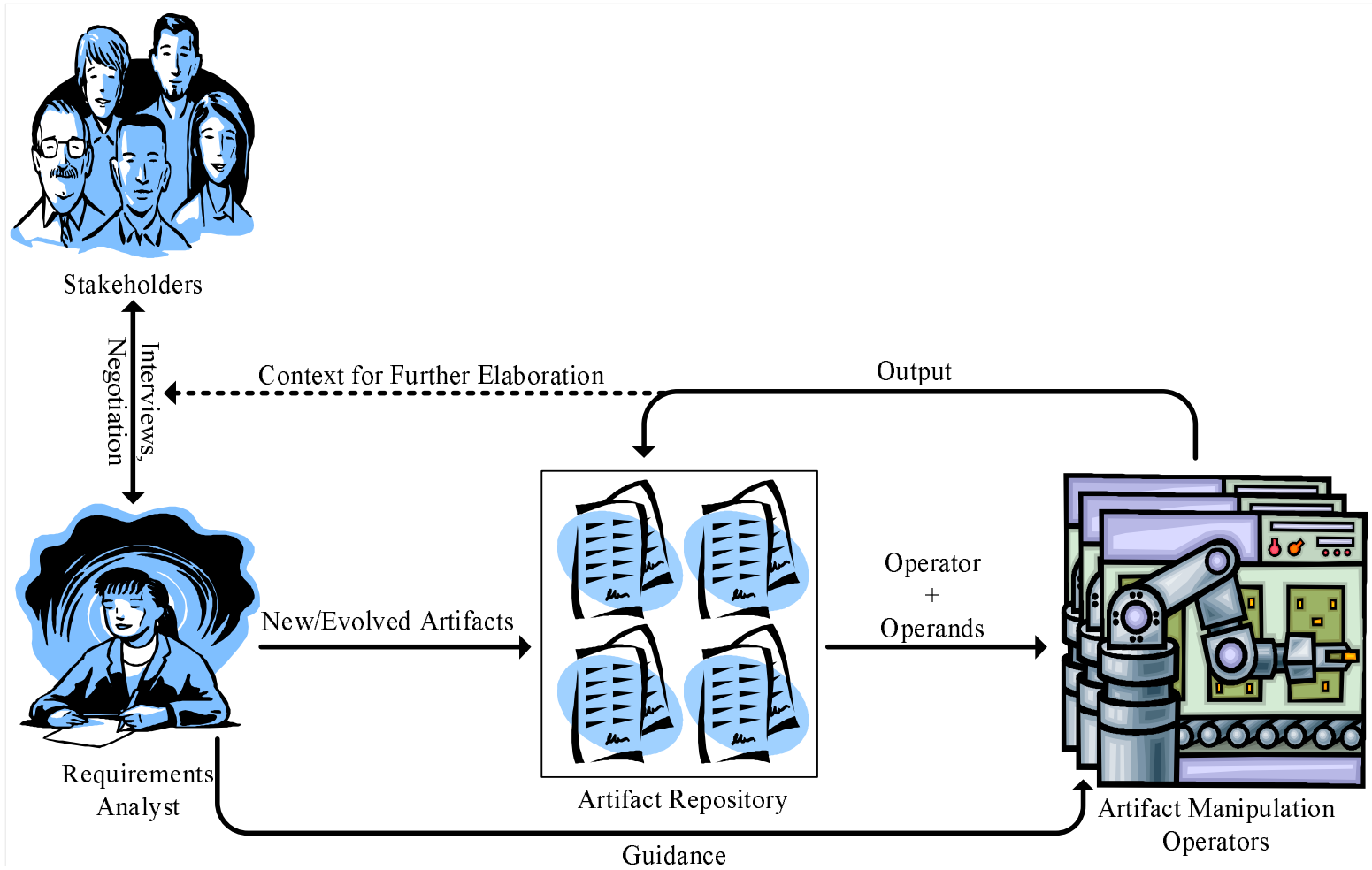
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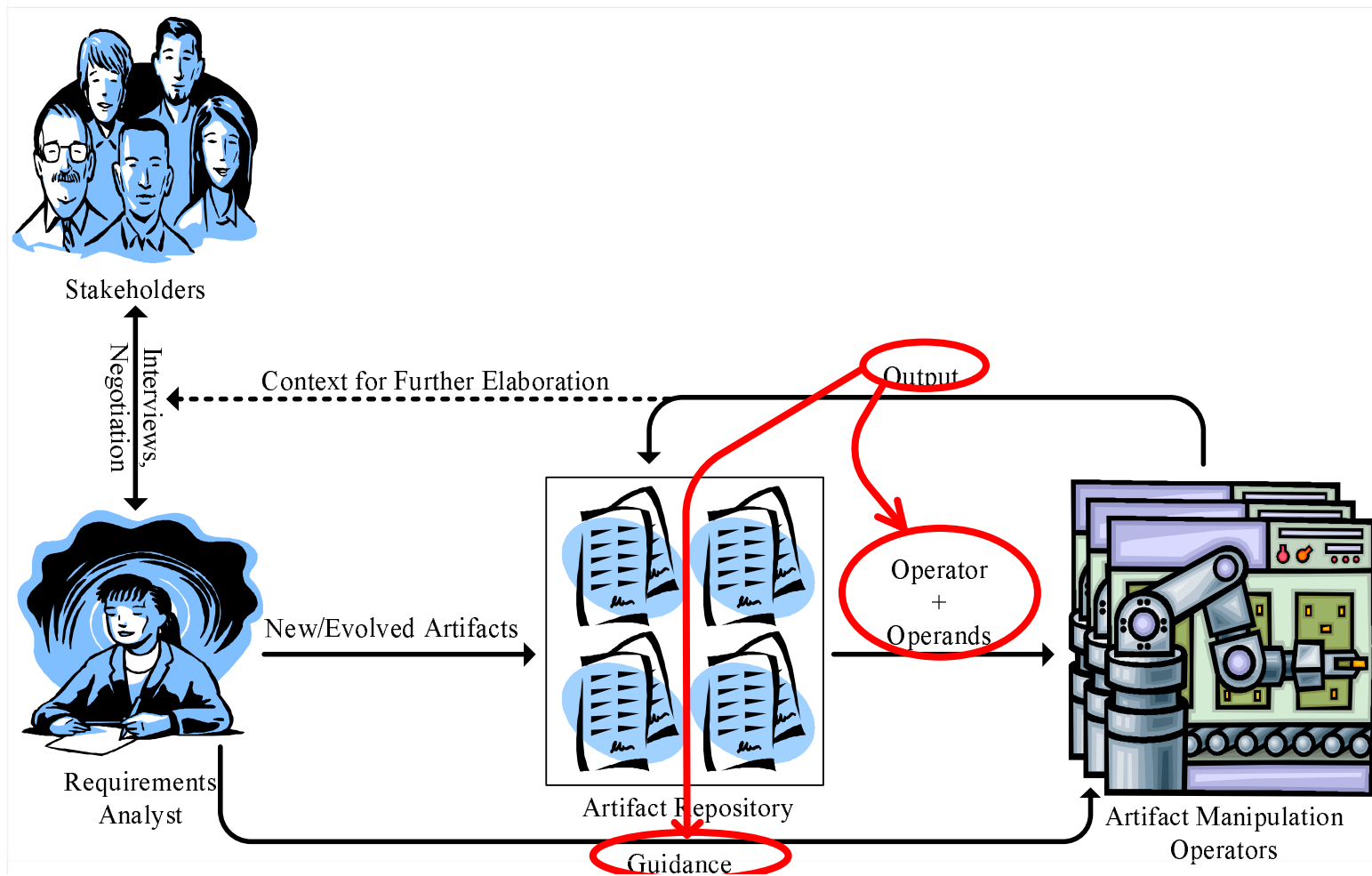
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November 8, 2005

# Synopsis



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➔ **Problem: Traceability from the output of an operator to its input**

# Model Management

## → What is model management?

➔ Keeping track of model interrelationships and providing a set of model manipulation operations

### ➤ Idea:

▣➔ Capturing conceptual data using **independent** but **interrelated** units

▣➔ Describing interrelations by **explicit mappings**

### ➤ Major operations:

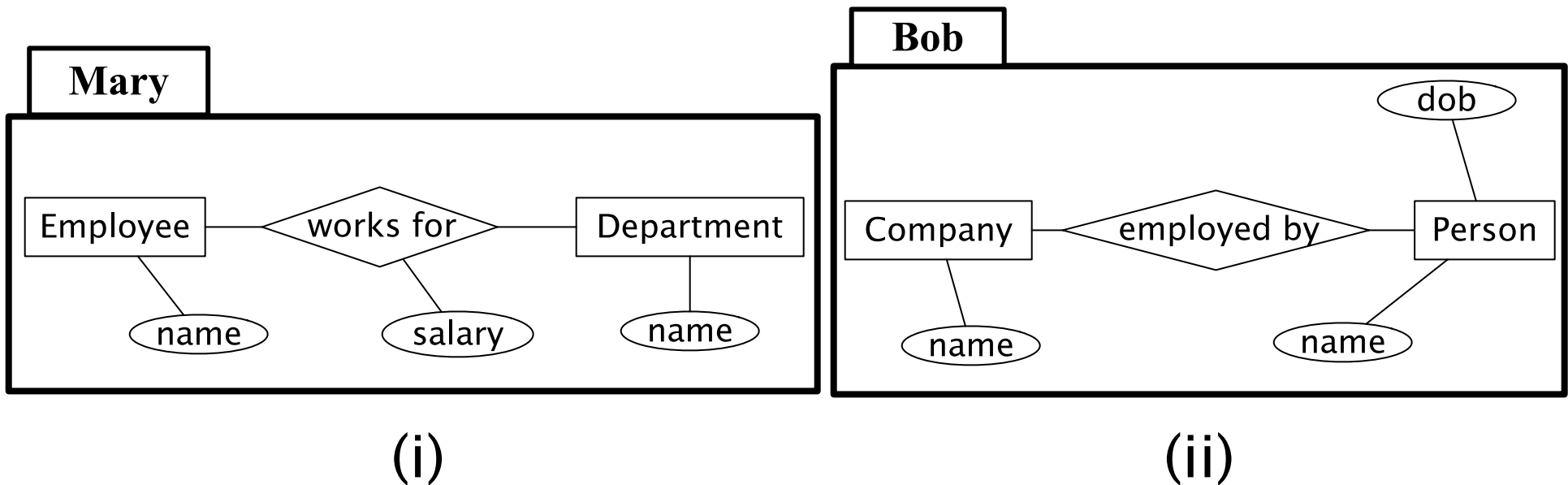
▣➔ Matching: finding correspondences between models

▣➔ Differencing: finding discrepancies between models

▣➔ Merging: consolidating models w.r.t. known relationships between them

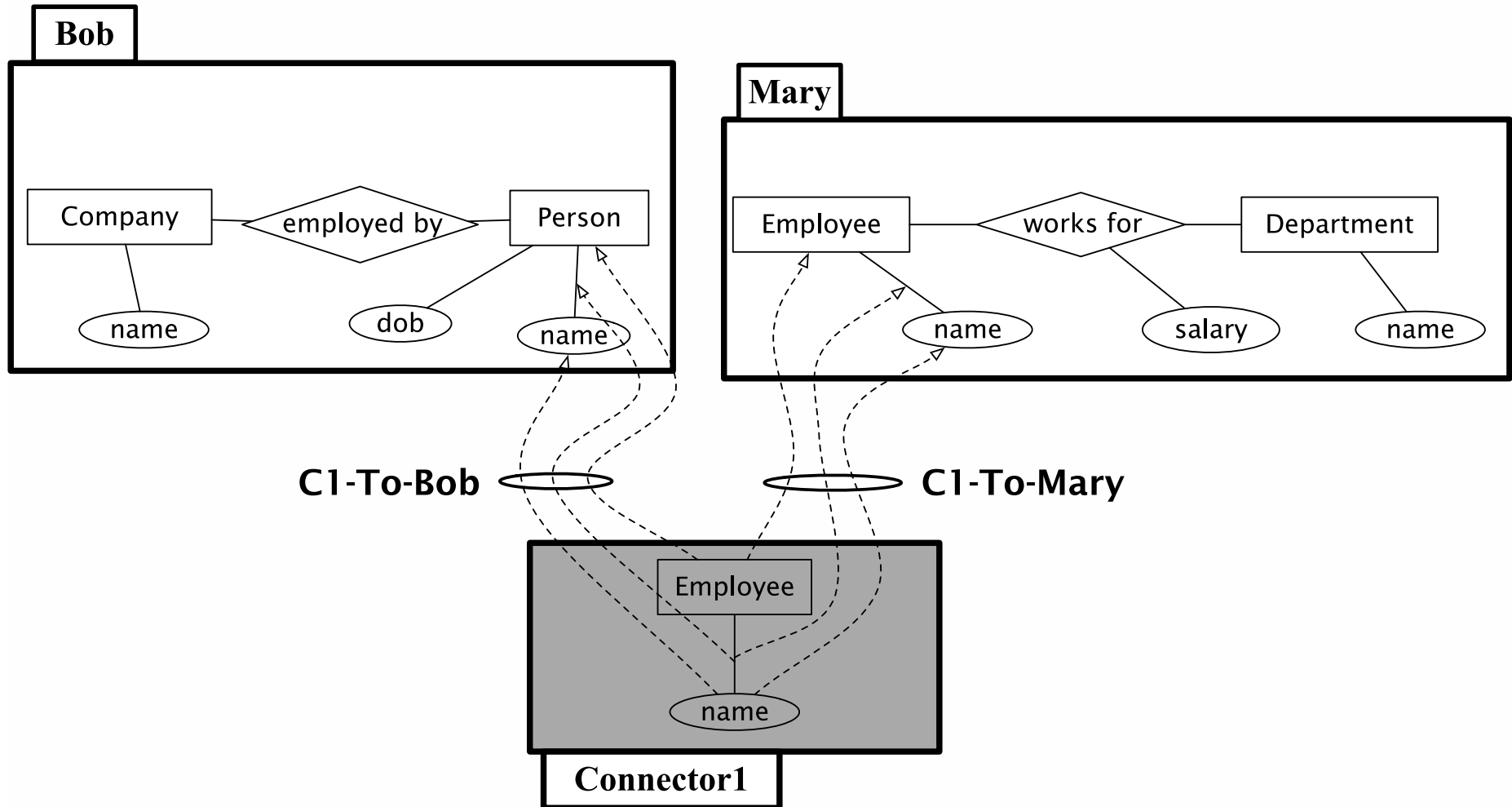
# Traceability in Viewpoint Merging

→ Example: Merging ER Viewpoints

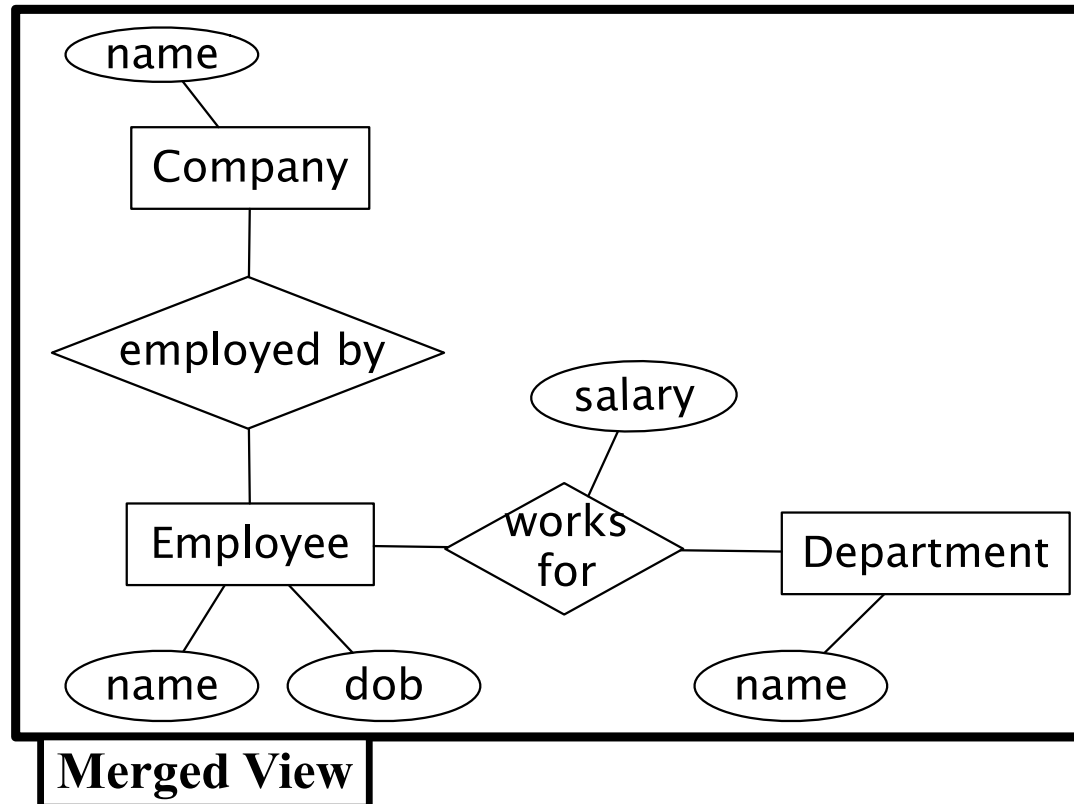


**Initial viewpoints of Mary and Bob**

# First Merge Attempt



# The Merged Viewpoint



→ **Concern I (origin traceability):**

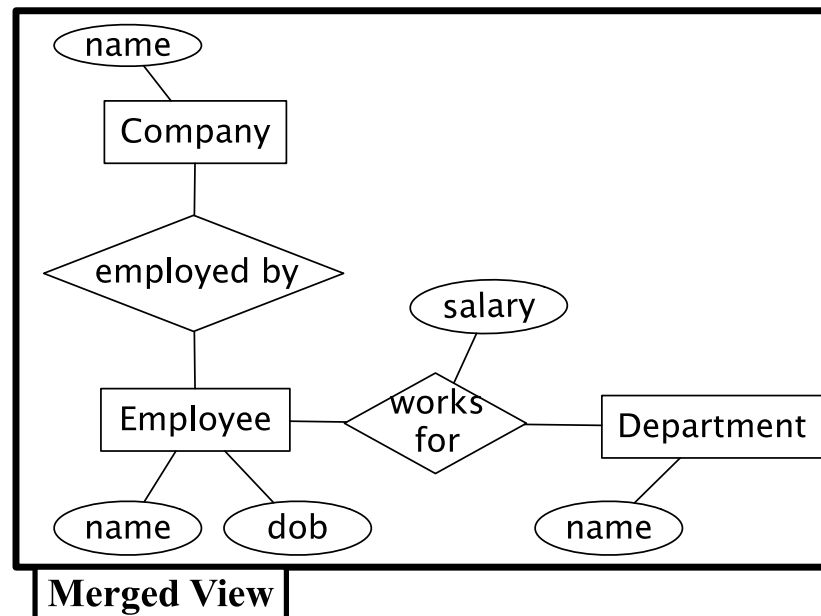
→ Where did each element originate from?

# Tracking Correspondence Assumptions

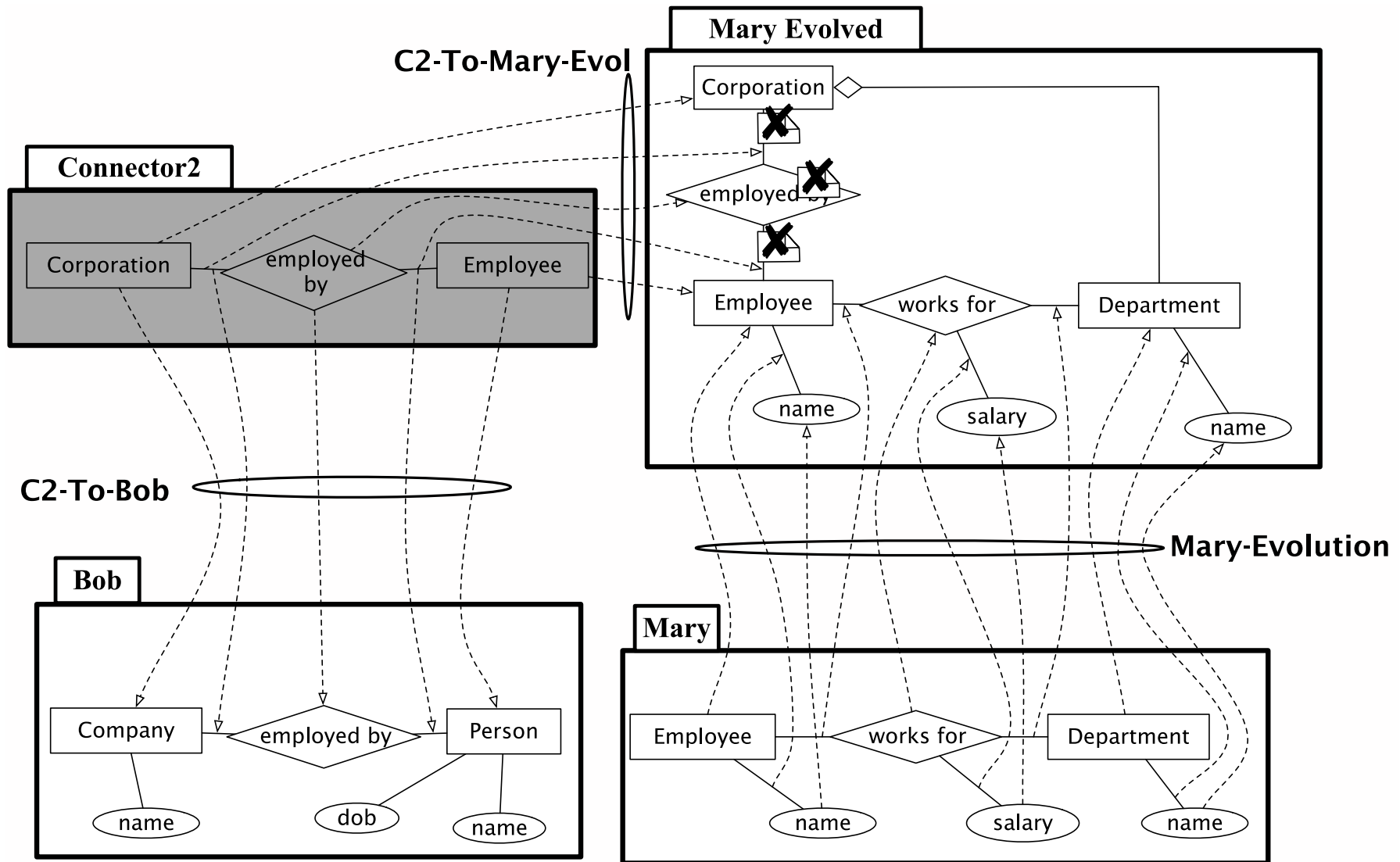
- ↳ Viewpoints evolve over time
  - hence, merge scenarios may get more complex
  - . . . and assumptions about correspondences may be scattered across several mappings

# Tracking Correspondence Assumptions

- ➔ Viewpoints evolve over time
  - hence, merge scenarios may get more complex
  - . . . and assumptions about correspondences may be scattered across several mappings

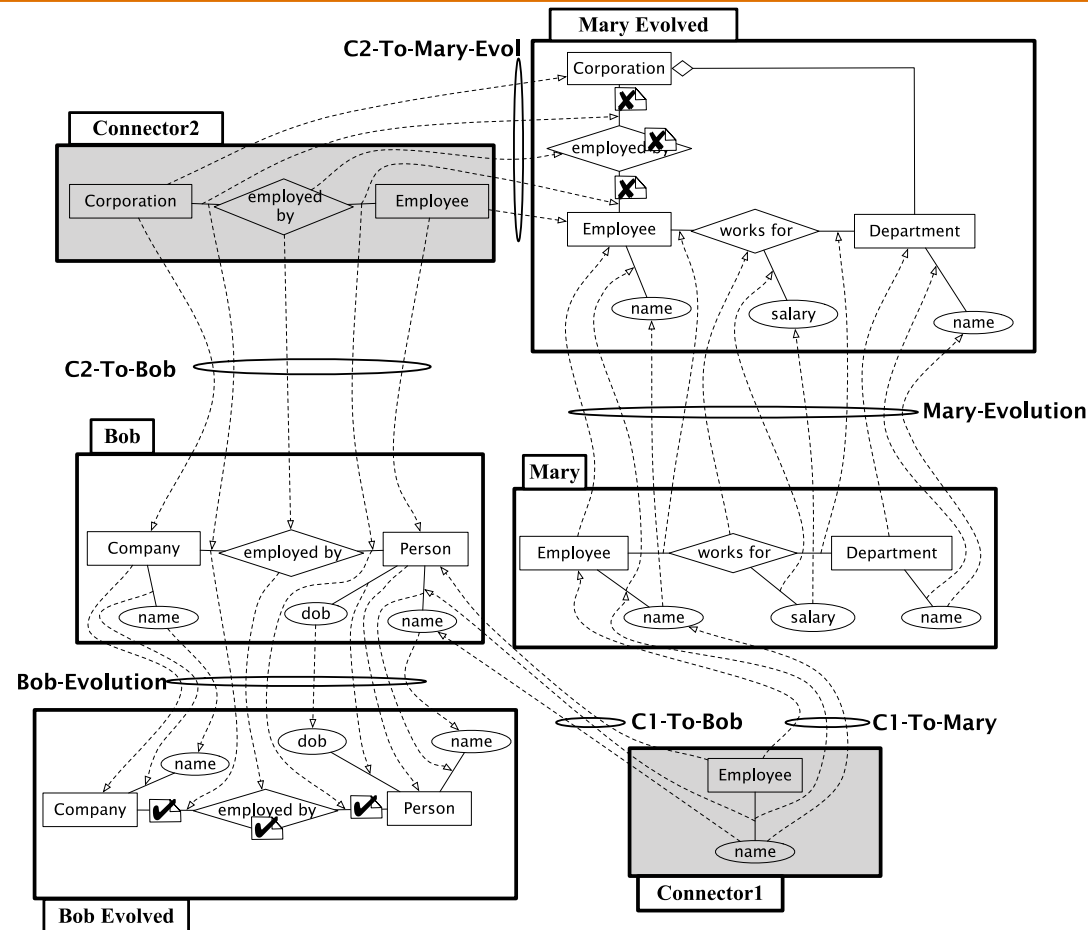


# Evolution – Part I





# The New Merge Hypothesis



→ **Concern II (assumption traceability):**

→ What correspondence assumptions were involved in each unification?

# The Merge Algorithm

## → Theory:

- ↳ Based on an algebraic concept called **colimit**
  - Colimits combine a set of models w.r.t. to their relationships as defined by a set of mappings

## → Main idea of the algorithm:

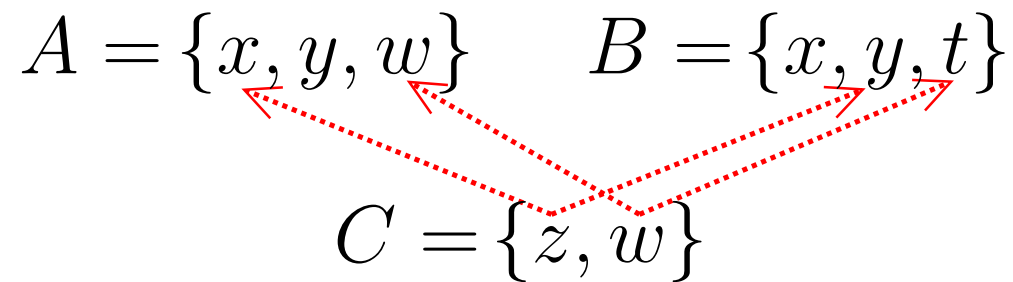
- ↳ Assume all model elements are distinct
- ↳ Unify elements deemed equal by the mappings

# Merging Sets

$$A = \{x, y, w\} \quad B = \{x, y, t\}$$
$$C = \{z, w\}$$

**The given interconnection diagram**

# Merging Sets

$$A = \{x, y, w\} \quad B = \{x, y, t\}$$
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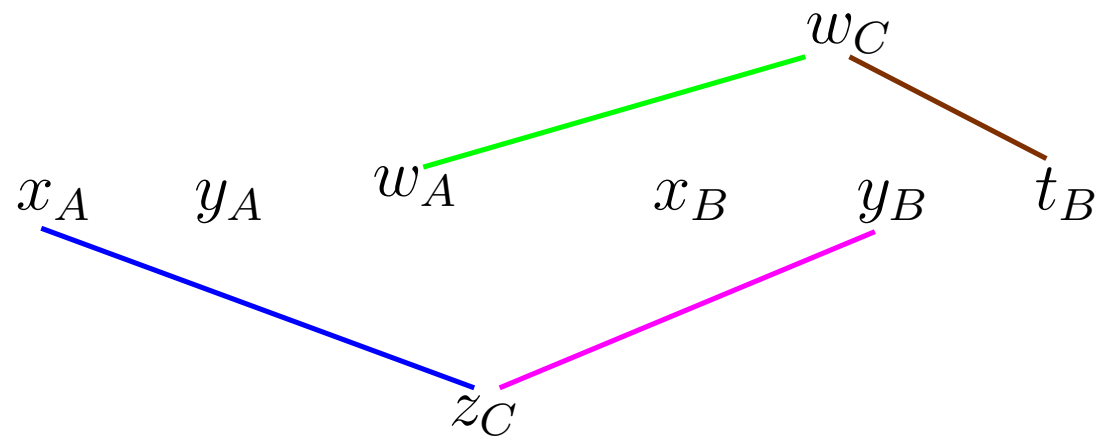
$$\begin{array}{ccccccc} & & & & & & w_C \\ & & & & & & \\ x_A & y_A & w_A & x_B & y_B & t_B & \\ & & & & & & \\ & & z_C & & & & \end{array}$$

**Compute the disjoint union**

# Merging Sets

$$A = \{x, y, w\} \quad B = \{x, y, t\}$$

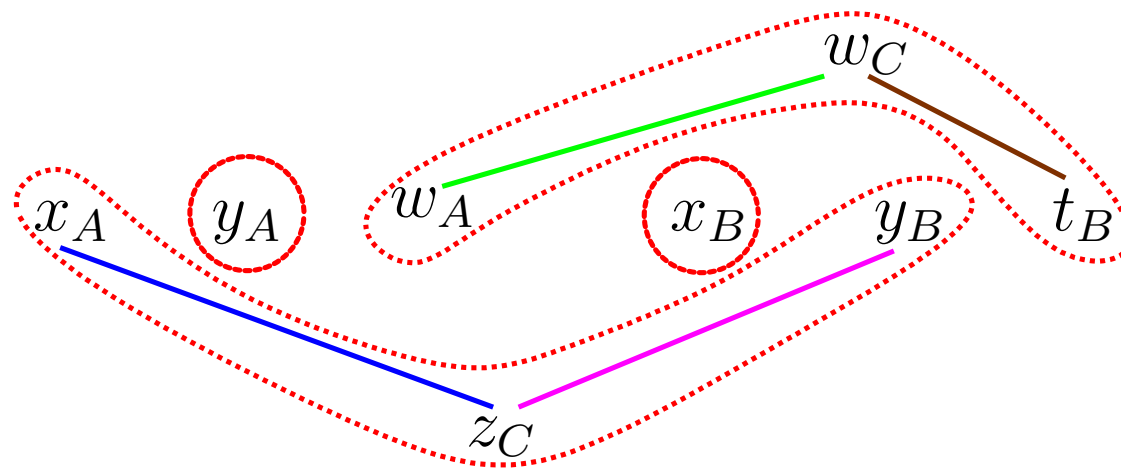
$$C = \{z, w\}$$



**Connect up the related pairs**  
**(This yields a unification graph)**

# Merging Sets

$$A = \{x, y, w\} \quad B = \{x, y, t\}$$
$$C = \{z, w\}$$



**Find the connected components**

# Generating Traceability Links

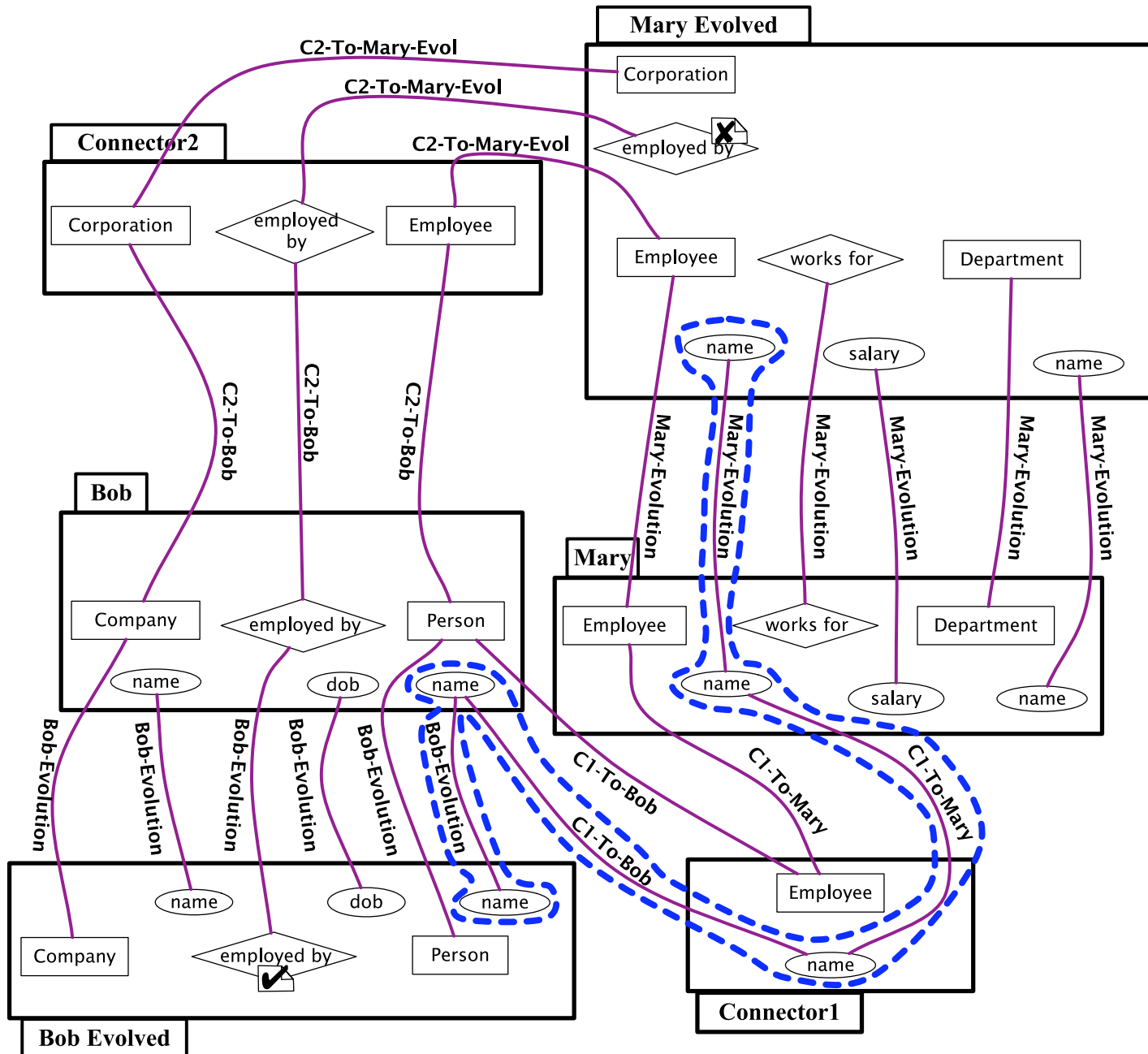
## → Origin Traceability

- ↪ For each merged element, the set of nodes in the connected component corresponding to the element

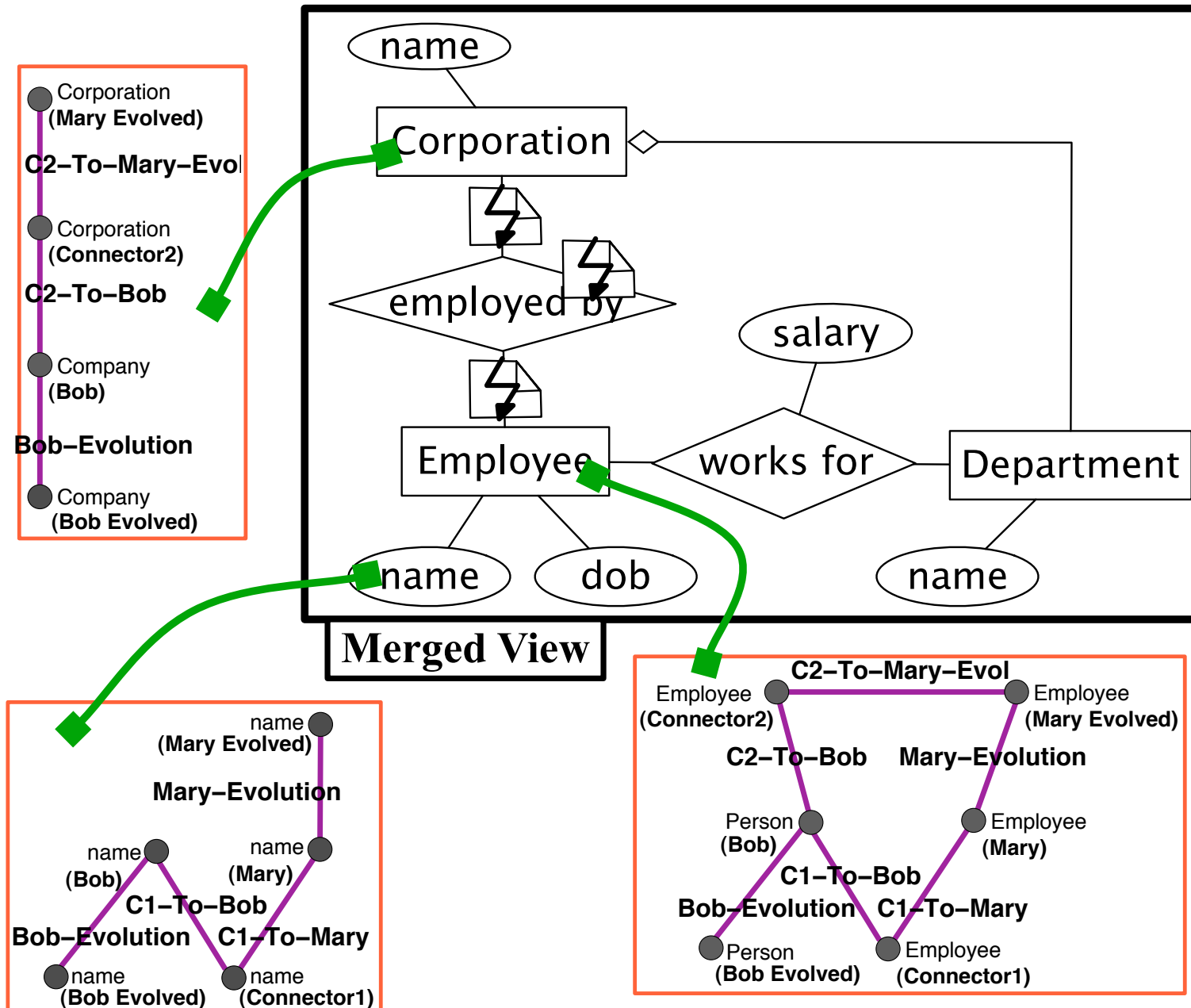
## → Assumption Traceability

- ↪ Problem: we did not keep track of **which** mapping induced each edge in the unification graph
  - Need to label each edge in the unification graph with the name of the mapping that induces it

# Unification Graph Example



# Stored Traceability Links



# Recap

## → Summary

### → A traceability framework for viewpoint merging

- independent of any particular modeling language
- scalable to arbitrary number of viewpoints and mappings

## → Limitations and weaknesses

### → Mappings are purely syntactic

- . . . hence, semantics-based traceability concerns need to be addressed separately

## Future Work

- ➔ Extending our viewpoint merging tool to:
  - **generate and visualize traceability links**
  - **support model-to-model navigation**
- ➔ Doing further experiments to surface other potential traceability concerns in viewpoint merging
- ➔ Exploiting traceability links for adaptive analysis of viewpoints
  - **Simple examples include: filtering and layout of the merges based on traceability data and stakeholders' preferences**

**Thank You!**

**Questions?**