

*Cyclic Proofs of Program Termination in  
Separation Logic*

James Brotherston<sup>1</sup>, Richard Bornat<sup>2</sup>,  
and Cristiano Calcagno<sup>1</sup>

<sup>1</sup>Imperial College, London

<sup>2</sup>Middlesex University, London

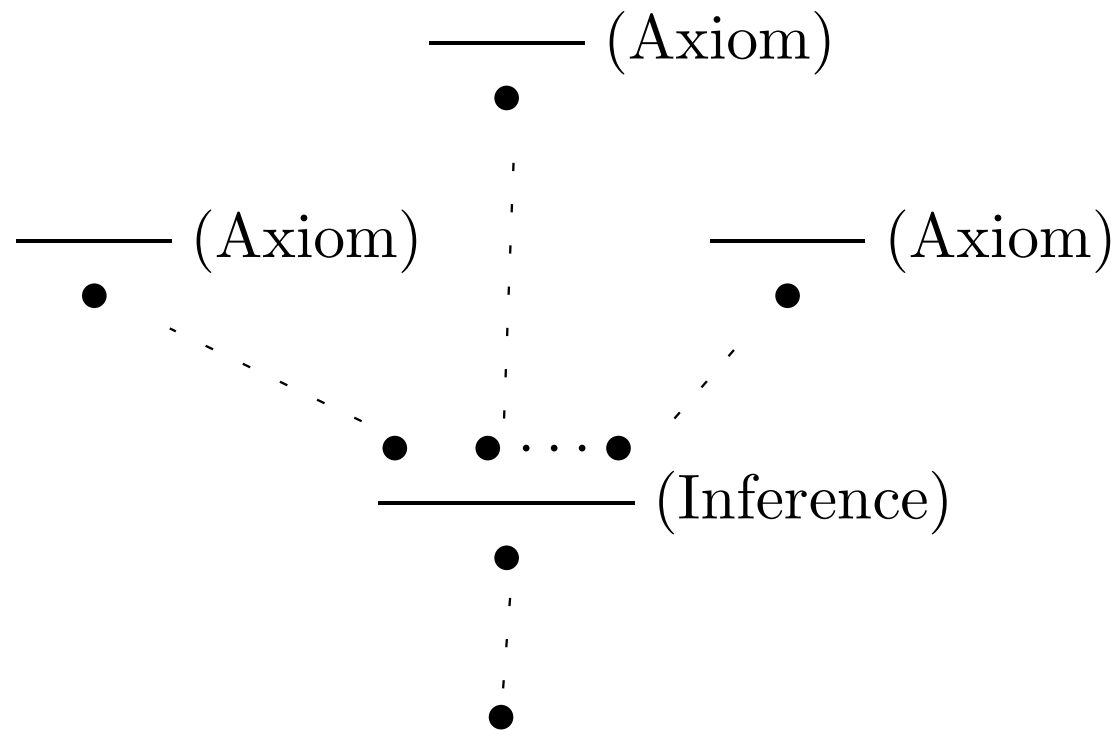
12 December, 2007

# Overview

- We give a **new method** for proving program termination, based upon **cyclic proof**.
- We consider **simple imperative programs** that may access the heap.
- We use **separation logic** to express termination preconditions, which typically also involve some **inductive definitions**.
- This work will appear in a paper with Bornat and Calcagno at POPL 2008.

## *Tree proof vs. cyclic proof (1)*

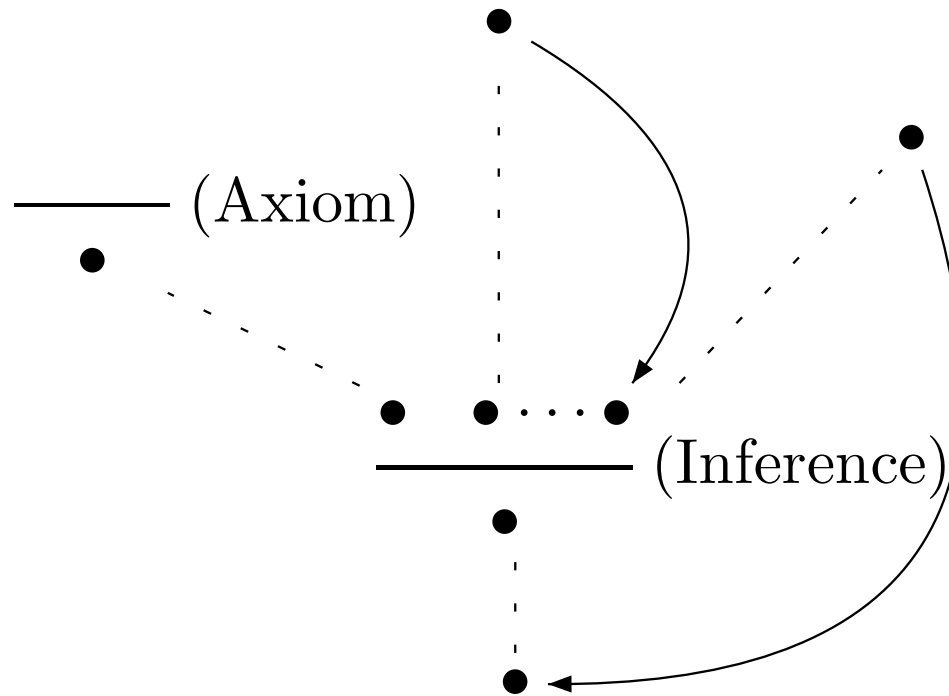
- Usually a proof is a **finite tree** of **sequents** ( $\bullet$ ):



- Soundness** of such proofs follows from the **local soundness** of each inference rule / axiom.

## Tree proof vs. cyclic proof (2)

- A **cyclic pre-proof** is a **regular, infinite tree** of sequents, usually represented as a rooted cyclic graph:



- Cyclic pre-proofs are **not sound** in general — we need some extra condition.
- **Cyclic proof** = cyclic pre-proof  $\mathcal{P}$  + soundness condition  $S(\mathcal{P})$ .

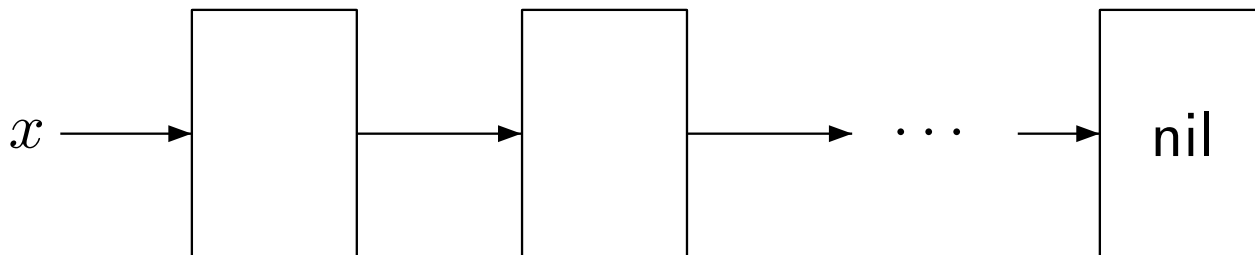
# *TOY-C: a simple imperative programming language*

$$\begin{aligned} E & ::= \text{nil} \mid x \ (x \in \text{Var}) \mid \dots \\ \text{Cond} & ::= E = E \mid E \neq E \\ C & ::= x := E \mid x := [E] \mid [E] := E \mid x := \text{new}() \\ & \quad \mid \text{free}(E) \mid \text{if } \text{Cond} \text{ goto } j \mid \text{stop} \end{aligned}$$

A **program** in TOY-C is a finite sequence  $1 : C_1; \dots n : C_n$ .

*Example (Linked list traversal)*

1 : if  $x = \text{nil}$  goto 4, 2 :  $x := [x]$ , 3 : goto 1, 4 : stop



## *Semantics of TOY-C (1)*

- We use a basic RAM-type model.
- Fix sets of **variables**  $\text{Var}$ , **values**  $\text{Val}$  and **locations**  $\text{Loc} \subset \text{Val}$ .
- A **stack** is a function  $s : \text{Var} \rightarrow \text{Val}$ .
- A **heap** is a partial, finitely-defined function  $h : \text{Loc} \rightarrow_{\text{fin}} \text{Val}$ . We write  $e$  for the empty heap and  $\circ$  for **composition** of disjoint heaps.
- A program **state** is then a triple  $(i, s, h)$ , where  $i$  is a index of the program,  $s$  is a stack and  $h$  is a heap.

## Semantics of TOY-C (2)

- The semantics of TOY-C programs is then given by a “one-step” binary relation  $\rightsquigarrow$  on program states. E.g.:

$$\frac{C_i \equiv x := [E] \quad \llbracket E \rrbracket s \in \text{dom}(h)}{(i, s, h) \rightsquigarrow (i + 1, s[x \mapsto h(\llbracket E \rrbracket s)], h)}$$

$$\frac{C_i \equiv x := [E] \quad \llbracket E \rrbracket s \notin \text{dom}(h)}{(i, s, h) \rightsquigarrow (\text{fault}, s, h)}$$

$$\frac{}{(\text{fault}, s, h) \rightsquigarrow (\text{fault}, s, h)}$$

- We write  $(i, s, h) \downarrow$  to mean there is no infinite  $\rightsquigarrow$ -sequence  $(i, s, h) \rightsquigarrow \dots$ , i.e., the program **terminates** when started in the state  $(i, s, h)$ .
- Program **faulting** is equated in our model with program **divergence**.

## Separation logic

- **Separation logic** adds new connectives to standard first-order logic, which let us reason about heap resource.
- The proposition **emp** expresses emptiness of the heap:

$$s, h \models \text{emp} \Leftrightarrow h = e$$

- $*$  characterises **heap composition**:

$$s, h \models F_1 * F_2 \Leftrightarrow h = h_1 \circ h_2 \text{ and } s, h_1 \models F_1 \text{ and } s, h_2 \models F_2$$

- $\text{--}*$  expresses a property of **(fresh) heap addition**:

$$s, h \models F_1 \text{--} * F_2 \Leftrightarrow s, h' \models F_1 \text{ and } h' \circ h \text{ defined} \\ \text{implies } s, h' \circ h \models F_2 \text{ for all heaps } h'$$

- We also need to alter the usual treatment of **predicates**: their interpretation should depend on the current heap.



## *Predicates in separation logic*

- For any predicate symbol  $P$  of arity  $k$  (say) we define its interpretation:

$$\llbracket P \rrbracket \subseteq \text{Pow}(\text{Heaps} \times \text{Val}^k)$$

whence we have:

$$s, h \models P\mathbf{t} \Leftrightarrow (h, s(\mathbf{t})) \in \llbracket P \rrbracket$$

- We have two types of predicate symbol: **ordinary** and **inductive**.
- The interpretation of each ordinary predicate symbol is fixed in our model.
- The interpretation of the inductive predicate symbols is determined by a given set of **inductive definitions**.

## *Inductive definitions: an example*

The following definition of an inductive predicate `ls` defines (possibly cyclic) **linked list segments**:

$$\frac{\text{emp}}{\text{ls } x \ x} \qquad \frac{x \mapsto x' * \text{ls } x' \ y}{\text{ls } x \ y}$$

where  $\mapsto$  is an ordinary predicate with interpretation:

$$\llbracket \mapsto \rrbracket = \{(h, (v_1, v_2)) \mid \text{dom}(h) = \{v_1\} \text{ and } h(v_1) = v_2\}$$

$\llbracket \text{ls} \rrbracket$  is then the **least fixed point** of the **monotone operator**  $\varphi_{\text{ls}}$  defined by:

$$\begin{aligned} \varphi_{\text{ls}}(X) &= \{(e, (v, v)) \mid v \in \text{Val}\} \\ &\cup \{(h_1 \circ h_2, (v, v')) \mid (h_1, (v, v'')) \in \llbracket \mapsto \rrbracket \\ &\quad \text{and } (h_2, (v'', v')) \in X\} \end{aligned}$$

## *A Hoare proof system for termination*

- We write **termination judgements**  $F \vdash_i \downarrow$  where  $i$  is a program label and  $F$  is a formula of separation logic.  $\Gamma(-)$  is notation for a “context”, given by:

$$\Gamma ::= - \mid \Gamma(-) \wedge F \mid \Gamma(-) * F$$

- $F \vdash_i \downarrow$  is **valid** if:

$$\text{for all } s, h. s, h \models F \text{ implies } (i, s, h) \downarrow$$

- We have two types of rules for termination judgements: **logical** rules, and **symbolic execution** rules.

## Logical rules

- Similar to the **left-introduction** rules in sequent calculus, e.g.:

$$\frac{\Gamma(F_1) \vdash_i \downarrow \quad \Gamma(F_2) \vdash_i \downarrow}{\Gamma(F_1 \vee F_2) \vdash_i \downarrow} (\vee\text{I}) \quad \frac{\Gamma(F_2) \vdash_i \downarrow}{\Gamma(F * (F_1 \multimap F_2)) \vdash_i \downarrow} F \vdash F_1 (\multimap\text{I})$$

- Each inductive predicate has a **case-split rule** obtained from its definition. E.g. the definition of **ls**:

$$\frac{\text{emp}}{\text{ls } x \ x} \quad \frac{x \mapsto x' * \text{ls } x' \ y}{\text{ls } x \ y}$$

gives the following case-split rule for **ls**:

$$\frac{\Gamma(t_1 = t_2 \wedge \text{emp}) \vdash_i \downarrow \quad \Gamma(t_1 \mapsto x * \text{ls } x \ t_2) \vdash_i \downarrow}{\Gamma(\text{ls } t_1 \ t_2) \vdash_i \downarrow} \quad x \text{ fresh (Case ls)}$$

## Symbolic execution rules

- These encapsulate the effect of **executing** a single program command. E.g.:

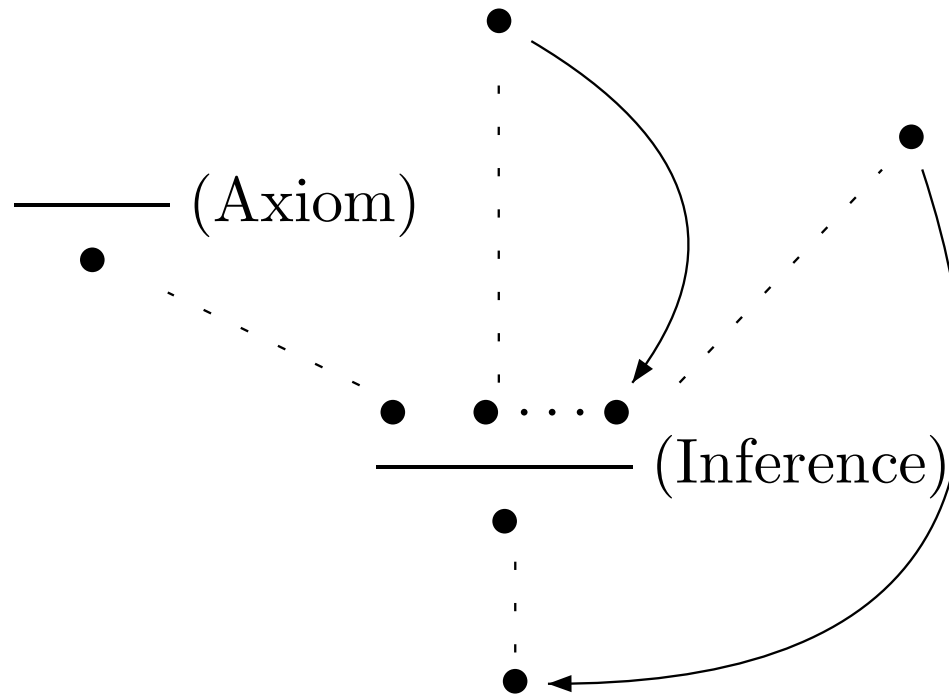
$$\frac{Cond \wedge F \vdash_j \downarrow \quad \neg Cond \wedge F \vdash_{i+1} \downarrow}{F \vdash_i \downarrow} C_i \equiv \text{if } Cond \text{ goto } j$$

$$\frac{x = t[x'/x] \wedge (E \mapsto t * F)[x'/x] \vdash_{i+1} \downarrow}{E \mapsto t * F \vdash_i \downarrow} C_i \equiv x := [E]$$

$$\frac{F \vdash_{i+1} \downarrow}{E \mapsto t * F \vdash_i \downarrow} C_i \equiv \text{free}(E)$$

## *Cyclic proofs of termination judgements*

- Recall the notion of a **cyclic pre-proof**:



- A **cyclic proof** is a pre-proof satisfying the following condition (stated informally):

*For every infinite path in the pre-proof one can “trace” some inductive definition along the path, and moreover this definition is **unfolded infinitely often** (using the case-split rules)*

# Properties of the proof system

## Theorem (Soundness)

If there is a cyclic proof of  $F \vdash_i \downarrow$  then  $F \vdash_i \downarrow$  is valid.

## Proposition

It is **decidable** whether a cyclic pre-proof is a cyclic proof, i.e. whether it satisfies the soundness condition.

## Theorem (Relative completeness)

If  $F \vdash_i \downarrow$  is valid then there is a formula  $G$  such that  $F \vdash G$  is a valid implication of separation logic and:

$$F \vdash G \text{ provable} \Rightarrow F \vdash_i \downarrow \text{ provable}$$

## Example: termination of linked list traversal

Recall the TOY-C program for traversing a linked list:

1 : **if**  $x = \text{nil}$  **goto** 4, 2 :  $x := [x]$ , 3 : **goto** 1, 4 : **stop**

We give a pre-proof of  $\text{ls } x \text{ nil} \vdash_1 \downarrow$ :

$$\begin{array}{c}
 \dfrac{(\dagger) \quad \text{ls } x \text{ nil} \vdash_1 \downarrow}{\text{ls } x \text{ nil} \vdash_3 \downarrow} \text{ (goto)} \\
 \dfrac{\text{ls } x \text{ nil} \vdash_3 \downarrow}{\top \wedge x \neq \text{nil} \wedge (x'' \mapsto x * \text{ls } x \text{ nil}) \vdash_3 \downarrow} \text{ (Weak)} \\
 \dfrac{\top \wedge x \neq \text{nil} \wedge (x'' \mapsto x * \text{ls } x \text{ nil}) \vdash_3 \downarrow}{x = x' \wedge x \neq \text{nil} \wedge (x'' \mapsto x' * \text{ls } x' \text{ nil}) \vdash_3 \downarrow} (=) \\
 \dfrac{x = x' \wedge x \neq \text{nil} \wedge (x'' \mapsto x' * \text{ls } x' \text{ nil}) \vdash_3 \downarrow}{x \neq \text{nil} \wedge (x \mapsto x' * \text{ls } x' \text{ nil}) \vdash_2 \downarrow} (- := [-]) \\
 \dfrac{x \neq \text{nil} \wedge (x \mapsto x' * \text{ls } x' \text{ nil}) \vdash_2 \downarrow}{x \neq \text{nil} \wedge \text{ls } x \text{ nil} \vdash_2 \downarrow} \text{ (Case ls)} \\
 \dfrac{x = \text{nil} \wedge \text{ls } x \text{ nil} \vdash_4 \downarrow \quad x \neq \text{nil} \wedge \text{ls } x \text{ nil} \vdash_2 \downarrow}{\text{ls } x \text{ nil} \vdash_1 \downarrow} \text{ (if)} \\
 (\dagger) \quad \text{ls } x \text{ nil} \vdash_1 \downarrow
 \end{array}$$

Note that there is only one infinite path, which goes around the loop and has a progressing trace (**highlighted**). So this pre-proof is indeed a cyclic proof.



## Reversing a “frying-pan” list

- The classical **list reverse** algorithm is:

1. $y := \text{nil}$	4. $x := [x]$	7. goto 2
2. if $x = \text{nil}$ goto 8	5. $[z] := y$	8. stop
3. $z := x$	6. $y := z$	

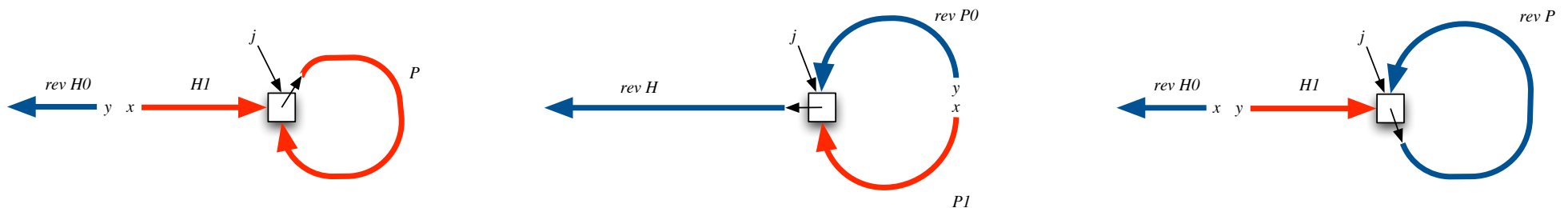
- The **invariant** for this algorithm given a cyclic list is:

$\exists k1, k2, k3.$

$(\text{ls } x \ j * \text{ls } y \ \text{nil} * j \mapsto k1 * \text{ls } k1 \ j) \vee$

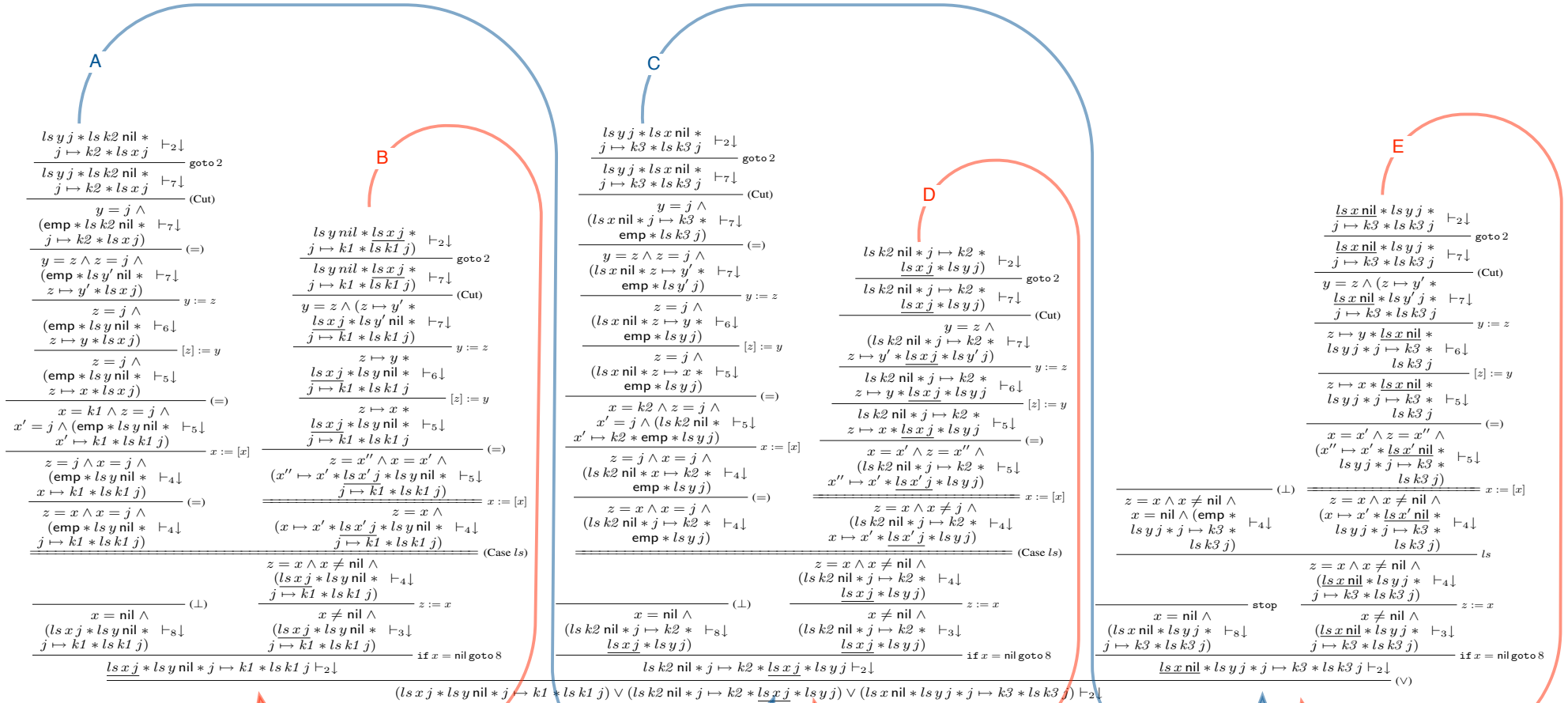
$(\text{ls } k2 \ \text{nil} * j \mapsto k2 * \text{ls } x \ j * \text{ls } y \ j) \vee$

$(\text{ls } x \ \text{nil} * \text{ls } y \ j * j \mapsto k3 * \text{ls } k3 \ j)$



- We want to prove that the invariant implies termination.

# Reversing a “frying-pan” list — the cyclic proof



# Endnotes



James Brotherston, Richard Bornat and Cristiano Calcagno.  
Cyclic proofs of program termination in separation logic.  
To appear in *Proceedings of POPL 2008*.



James Brotherston.  
Formalised inductive reasoning in the logic of bunched implications.  
In *Proceedings of SAS 2007*.



James Brotherston and Alex Simpson.  
Complete sequent calculi for induction and infinite descent.  
In *Proceedings of LICS 2007*.



Josh Berdine, Cristiano Calcagno and Peter O'Hearn.  
Symbolic execution with separation logic.  
In *Proceedings of APLAS 2005*.



John C. Reynolds.  
Separation logic: a logic for shared mutable data structures.  
In *Proceedings of LICS 2002*.