Undecidability of propositional separation logic and its neighbours

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Archetypal heap models are ⟨H, ∘, {e}⟩⟩, where
H = L →_{fin} RV is a set of heaps, e is the empty heap, and
∘ is (partial) union of disjoint heaps.
(Variations: stacks-and-heaps, heaps with permissions)

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 - but, when M is given in advance, we have no such freedom!

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- 1. BI \subset BBI \subset BBI+eW \subset BBI+W, and both BI, BBI+W are decidable;
- 2. BBI, BBI+eW are (obviously) incomplete wrt. validity in particular concrete models.

machine M terminates from configuration C









Finite valuations

Undecidability is intimately related to infinite valuations of the propositional variables (as sets of model elements):

Theorem

There is a sequent $\mathcal{F}_{\mathcal{M},\mathcal{C}}$ such that, for any heap-like model M:

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So, to obtain decidable fragments of separation logic, one could:

- 1. give up infinite valuations (Calcagno et al., FSTTCS'01);
- 2. restrict the formula language (Berdine et al., FSTTCS'04).

For the **purely propositional** fragment of separation logic, we have the following new results:

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- validity in such a model cannot be approximated by finite valuations for propositional variables (which imposes restrictions on decidable fragments);
- validity in various classes of models is undecidable;
- and provability in various axiomatisations (BBI, BBI+eW, CBI, CBI+eW,...) is undecidable too.

Separation logic vs. linear logic

Separation logic obeys two principles which are highly unorthodox from the perspective of linear logic:

1. The usual distributivity law

$$A \wedge (B \vee C) = (A \wedge B) \vee (A \wedge C)$$

2. The exact equality

$$\llbracket A \ast B \rrbracket = \llbracket A \rrbracket \cdot \llbracket B \rrbracket$$

(In linear logic we typically have $\llbracket A * B \rrbracket \not\subseteq \llbracket A \rrbracket \cdot \llbracket B \rrbracket$.) These two facts are entirely responsible for the undecidability of separation logic!