Background: I/O Concurrency

Brad Karp
UCL Computer Science

CS GZ03 / M030
1st October 2014
Outline

• “Worse Is Better” and Distributed Systems

• Problem: Naïve single-process server leaves system resources idle; I/O blocks
  – Goal: I/O concurrency
  – Goal: CPU concurrency

• Solutions
  – Multiple processes
  – One process, many threads
  – Event-driven I/O (not in today’s lecture)
Review: How Do Servers Use Syscalls?

- Consider server_1() web server (in handout)
Review: How Do Servers Use Syscalls?

Server waits for each resource in turn
Each resource largely idle
What if there are many clients?
Performance and Concurrency

• Under heavy load, server_1():
  – Leaves resources idle
  – ...and has a lot of work to do!

• Why?
  – Software poorly structured!
  – What would a better structure look like?
Solution: I/O Concurrency

• Can we overlap I/O with other useful work? Yes:
  – Web server: if files in disk cache, I/O wait spent mostly blocked on write to network
  – Networked file system client: could compile first part of file while fetching second part

• Performance benefits potentially huge
  – Say one client causes disk I/O, 10 ms
  – If other clients’ requests in cache, could serve 100 other clients during that time!
One Process
May Be Better Than You Think

• OS provides I/O concurrency to application transparently when it can, e.g.,
  – Filesystem does read-ahead into disk buffer cache; write-behind from disk buffer cache
  – Networking code copies arriving packets into application’s kernel socket buffer; copies app’s data into kernel socket buffer on write()
I/O Concurrency with Multiple Processes

- Idea: start new UNIX process for each client connection/request
- Master process assigns new connections to child processes
- Now plenty of work to keep system busy!
  - One process blocks in syscall, others can process arriving requests
- Structure of software still simple
  - See server_2() in webserver.c
  - fork() after accept()
  - Otherwise, software structure unchanged!
Multiple Processes: More Benefits

- **Isolation**
  - Bug while processing one client’s request leaves other clients/requests unaffected
  - Processes do interact, but OS arbitrates (e.g., “lock the disk request queue”)

- **CPU concurrency for “free”**
  - If more than one CPU in box, each process may run on one CPU
CPU Concurrency

- Single machine may have multiple CPUs, one shared memory
  - Symmetric Multiprocessor (SMP) PCs
  - Intel Core Duo
- I/O concurrency tools often help with CPU concurrency
  - But way more work for OS designer!
- Generally, CPU concurrency way less important than I/O concurrency
  - Factor of 2X, not 100X
  - Very hard to program to get good scaling
  - Easier to buy 2 machines (see future lectures!)
Problems with Multiple Processes

• fork() may be expensive
  – Memory for new address space
  – 300 us minimum on modern PC running UNIX

• Processes fairly isolated by default
  – Memory not shared
  – How do you build web cache on server visible to all processes?
  – How do you simply keep statistics?
Concurrency with Threads

• Similar to multiple processes
• Difference: one address space
  – All threads share same process’ memory
  – One stack per thread, inside process
• Seems simple: single-process structure!
• Programmer needs to use locks
• One thread can corrupt another (i.e., no cross-request isolation)
Concurrency with Threads

![Diagram of concurrency with threads](image)

- **Kernel**
  - Filesystem
  - Disk Driver
- **Hardware**

**User Space**

- **App1**
  - `t1` stack
- **App2**
  - `t2` stack

**Stacks**

- `t1` stack
- `t2` stack

**Threads**

- `t1`
- `t2`
Threads: Low-Level Details Are Hard!

• Suppose thread calls read() (or other blocking syscall)
  – Does whole process block until I/O done?
  – If so, no I/O concurrency!

• Two solutions:
  – Kernel-supported threads
  – User-supported threads
Kernel-Supported Threads

• OS kernel aware of each thread
  – Knows if thread blocks, e.g., disk read wait
  – Can schedule another thread

• Kernel requirements:
  – Per-thread kernel stack
  – Per-thread tables (e.g., saved registers)

• Semantics:
  – Per-process: address space, file descriptors
  – Per-thread: user stack, kernel stack, kernel state
Kernel-Supported Threads

Kernel

User Space

App1

App2

Filesystem

Disk Driver

Hardware

stack, table

stack, table

stack, table

stack, table

N

M

0

0
Kernel Threads: Trade-Offs

• Kernel can schedule one thread per CPU
  – Fits our goals well: both CPU and I/O concurrency

• But kernel threads expensive, like processes:
  – Kernel must help create each thread
  – Kernel must help with thread context switch!
    • Which thread took a page fault?
  – Lock/unlock must invoke kernel, but heavily used

• Kernel threads not portable; not offered by many OSes
User-Level Threads

• Purely inside user process; kernel oblivious
• Scheduler within user process for process’ own threads
  – In addition to kernel’s process scheduler
• User-level scheduler must
  – Know when thread makes blocking syscall
  – Not block process; switch to another thread
  – Know when I/O done, to wake up original thread
User-Level Thread Implementation
User-Level Threads: Details

- Apps linked against thread library
- Library contains “fake” read(), write(), accept(), &c. syscalls
- Library can start non-blocking syscall operations
- Library marks threads as waiting, switches to runnable thread
- Kernel notifies library of I/O completion and other events; library marks waiting thread runnable
User-Level Threads: read() Example

```c
read() {
    tell kernel to start read;
    mark thread waiting for read;
    sched();
}

sched() {
    ask kernel for I/O completion events;
    mark corresponding threads runnable;
    find runnable thread;
    restore registers and return;
}
```
User-Level Threads: Event Notification

- Events thread library needs from kernel:
  - new network connection
  - data arrived on socket
  - disk read completed
  - socket ready for further write()s

- Resembles miniature OS inside process!

- Problem: user-level threads demand significant kernel support:
  - non-blocking system calls
  - uniform event delivery mechanism
Event Notification in Typical OSes

- Usually, event notification only partly supported; e.g., in UNIX:
  - new TCP connections, arriving TCP/pipe/tty data: YES
  - filesystem operation completion: NO

- Similarly, not all syscalls can be started without waiting, e.g., in UNIX:
  - connect(), read()/write() on socket
  - open(), stat(): NO
  - read() from disk: SOMETIMES (e.g., aio_read())
Non-blocking System Calls: Hard to Implement

- Typical syscall implementation, inside the kernel, e.g., for `read()` (sys_read.c):

```c
sys_read(fd, user_buffer, n) {
    // read the file’s i-node from disk
    struct inode *i = alloc_inode();
    start_disk(..., i);
    wait_for_disk(i);
    // the i-node tells us where the data are; read it.
    struct buf *b = alloc_buf(i->...);
    start_disk(..., b);
    wait_for_disk(b);
    copy_to_user(b, user_buffer);
}
```
Typical syscall implementation, inside the kernel, e.g., for read() (sys_read.c):

```c
sys_read(fd, user_buffer, n) {
    // read the file's i-node from disk
    struct inode *i = alloc_inode();
    start_disk(…, i);
    wait_for_disk(i);
    // the i-node tells us where the data are; read it.
    struct buf *b = alloc_buf(i->…);
    start_disk(…, b);
    wait_for_disk(b);
    copy_to_user(b, user_buffer);
}
```

Why not just return to user program instead of calling `wait_for_disk()`?

How will kernel know where to continue?

In user space? In kernel?
Non-blocking System Calls: Hard to Implement

- Typical syscall implementation, inside the kernel,

```c
sys_read(fd, user_buffer, n) {
    // read the file's i-node from disk
    struct inode *i = alloc_inode();
    start_disk(…, i);
    wait_for_disk(i);
    // the i-node tells us where the data are; read it.
    struct buf *b = alloc_buf(i->…);
    start_disk(…, b);
    wait_for_disk(b);
    copy_to_user(b, user_buffer);
}
```

Why not just return to user program instead of calling wait_for_disk()? How will kernel know where to continue? In user space? In kernel?

```c
wait_for_disk(i);
```

Problem: Keeping state for complex, multi-step operations

```c
start_disk(fd, b);
wait_for_disk(b);
copy_to_user(b, user_buffer);
```
User-Threads: Implementation Choices

• Live with **only partial support for user-level threads**

• New operating system with **totally different syscall interface**
  – One syscall per non-blocking “sub-operation”
  – Kernel doesn’t need to keep state across multiple steps
  – e.g., `lookup_one_path_component()`

• Microkernel: no system calls, just messages to servers, with non-blocking communication
Threads: Programming Difficulty

• Sharing of data structures in one address space
• Even on single CPU, thread model necessitates CPU concurrency
  – Locks often needed for mutual exclusion on data structures
  – May only have wanted to overlap I/O wait!
• Events usually occur one-at-a-time
  – Can we do CPU sequentially, and overlap only wait for I/O?
  – Yes: event-driven programming
Event-Driven Programming

• Foreshadowed by user-level threads implementation
  – Organize software around event arrival
• Write software in state-machine style
  – “When event X occurs, execute this function.”
• Library support for registering interest in events (e.g., data available to read())
• Desirable properties:
  – Serial nature of events preserved
  – Programmer sees only one event/function at a time